The expected work will exploit and improve a perception algorithm developed in the Chroma team, the CMCDOT. This grid-based approach is a Bayesian
filtering system for environment representation through dynamic occupation grids, allowing parallel estimation of occupation probabilities for each cell, inference of velocities and prediction of the risk of collision. New solutions to add semantic information based on deep learning techniques will be also considered and analyzed. An important part of the thesis will be then dedicated to formally validate the obtained results through tests on a realistic autonomous driving simulator (e.g., Carla) and real experiments conducted with our fully autonomous car (Renault Zoe).


Principales activités
Main activities:
- Definition of criteria for the evaluation of dynamic occupation grids and semantic maps.
- Proposal of a formal validation methodology for Bayesian perception and prediction methods.
- Study of behavioral modeling of the simulated vehicle environment (e.g., dynamic, static obstacles, road configuration, etc.) for the automatic generation of relevant, borderline case scenarios.
- Formal modeling of the critical subsystems and verification of their functional properties (e.g., absence of deadlocks, detection and correct prediction of collisions, etc.).
- Definition and development of a hybrid simulation function with injection of real data and integration into a formal validation model for co-simulation.
- Generation of conformance test cases in controlled environments from a formal model of the environment and the system for the evaluation of KPIs. Study of the coverage of relevant tests against the formal model.

Compétences
The candidate will have a Master 2 level or equivalent, in computer science, AI or robotics. Technical skills: experience with ROS and C++; knowledge of formal methods for concurrent systems and deep learning techniques is a plus. Languages: proficiency in English; knowledge of French also welcome. Relational skills: team working.

Avantages
- Subsidized meals
- Partial reimbursement of public transport costs
- Leave: 7 weeks of annual leave + 10 extra days off due to RTT (statutory reduction in working hours) + possibility of exceptional leave (sick children, moving home, etc.)
- Possibility of teleworking (after 6 months of employment) and flexible organization of working hours
- Professional equipment available (videoconferencing, loan of computer equipment, etc.)
- Social, cultural and sports events and activities
- Access to vocational training
- Social security coverage

Rémunération
1st and 2nd year: 1 982 euros brut/month
3rd year: 2 085 euros brut / month